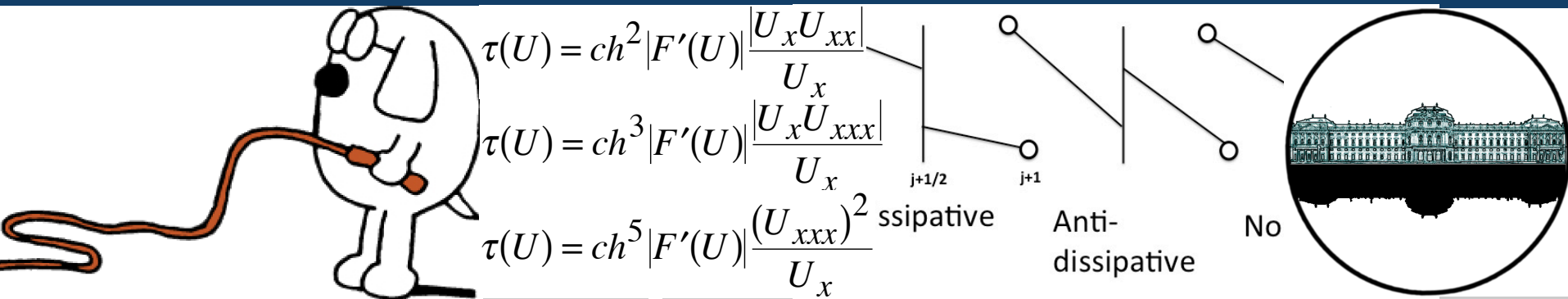


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# Evolution Equations for Developing Improved High-Resolution Schemes

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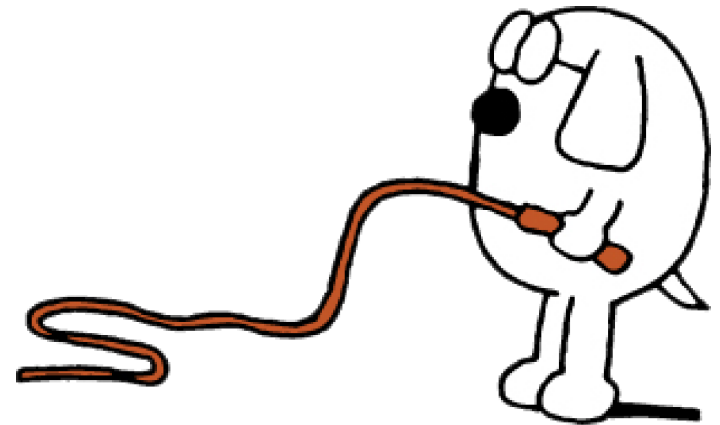
SAND 2015-7115C

# The Three Goals for this Talk

- **Goal 1:** Why have second-order monotonicity-preserving method been so dominant and remain so?
- **Goal 2:** What can the method of modified equations teach us about these numerical methods?
- **Goal 3:** What is needed to move beyond monotonicity preserving methods to something “better” and more accurate?

# High-Resolution Methods

- These methods have provided an enormous upgrade in computational performance over “classical” methods.



- **The Dogbert Principle:** *“Logically all things are created by a combination of simpler, less capable components”*

*(see Laney in Computational Gasdynamics)*

“Any sufficiently advanced technology is  
indistinguishable from magic.”  
– Arthur C. Clarke

# Three reasons why the second-order methods were so dominantly successful.

- **Reason 1:** Robustness without inducing a viscosity that implicitly renders all solutions “laminar” and a stable hyperviscous regularization that provides turbulent “looking” solutions. (ILES happened)
- **Reason 2:** A very robust nonlinear stability principle (that even allows linearly unstable methods to be used e.g., steepeners).
- **Reason 3:** “Huge” gains in accuracy/resolution/fidelity over previous methods.

**All these conclusions come from modified equation analysis!**

# A second-order Godunov method uses piecewise linear polynomials.

- A first order polynomial (PLM) or a second-order polynomial uses the cell average and the cell edge values (PPM),

$$\mathbf{P}_j(\theta) = \mathbf{P}_0 + \mathbf{P}_1\theta$$

$$\mathbf{P}_0 = \mathbf{U}_j^n; \mathbf{P}_1 = S_j$$

$$\mathbf{P}_j(\theta) = \mathbf{P}_0 + \mathbf{P}_1\theta + \mathbf{P}_2\theta^2$$

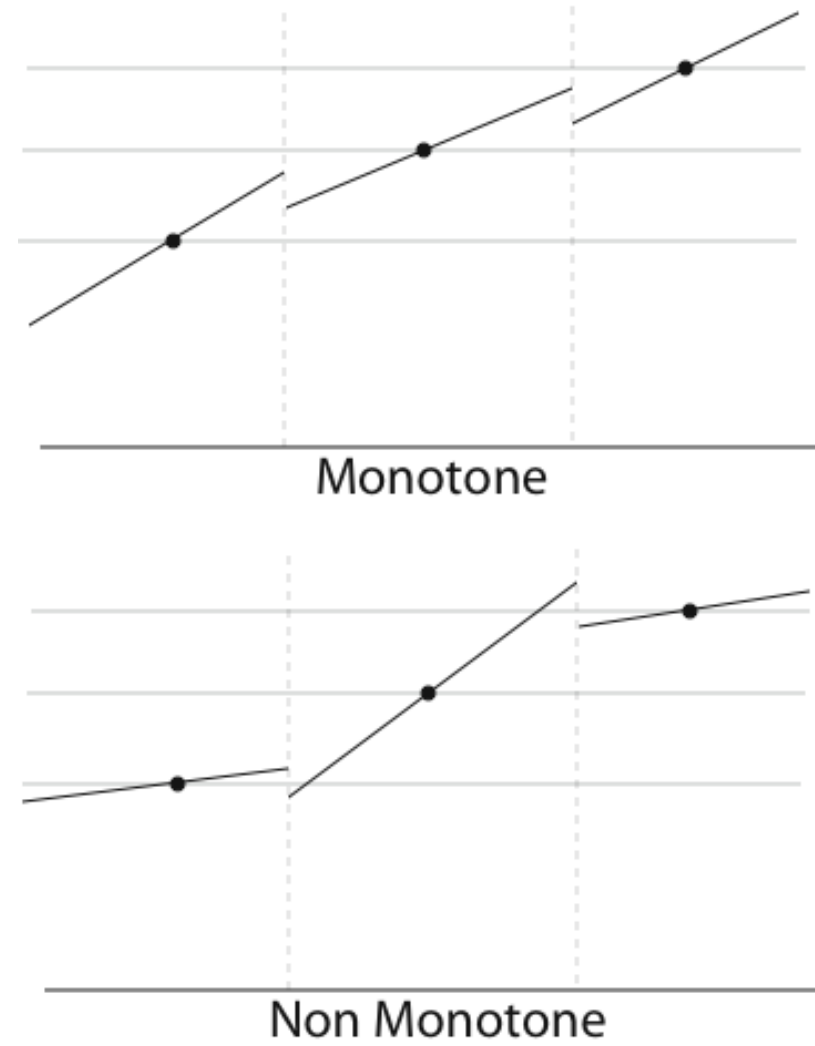
$$\mathbf{P}_0 = \mathbf{U}_j^n - \frac{1}{12}\mathbf{P}_2; \mathbf{P}_1 = U_{j+1/2} - U_{j-1/2}; \mathbf{P}_2 = 3(U_{j+1/2} + U_{j-1/2}) - 6U_j$$

- Several key requirements are necessary for this to be useful:

- Conservation  $U_j = \int \mathbf{P}_j(\theta) d\theta = \mathbf{P}_0$
- Accuracy  $U_{j\pm 1/2} = U(x_{j\pm 1/2}) + \mathcal{O}(\Delta x^n)$
- Boundedness (monotonicity)

# The key to using these reconstructions is keeping the polynomials monotone.

- The original statement is heuristic: the reconstruction should be bounded by the neighboring data.
- Later, time-dependence will be entertained, the time integrated edge values must be bounded.



There is a wide variety of “slopes” that can be used with PLM (many from the TVD schemes).

- Here is a slew of different recipes

- Minmod  $S_j = \min \text{mod} \left[ \Delta_{j-1/2}, \Delta_{j+1/2} \mathbf{U} \right]$

- Van Leer 
$$S_j = \frac{|\Delta_{j+1/2} \mathbf{U}| \Delta_{j-1/2} \mathbf{U} + |\Delta_{j-1/2} \mathbf{U}| \Delta_{j+1/2} \mathbf{U}}{|\Delta_{j-1/2} \mathbf{U}| + |\Delta_{j+1/2} \mathbf{U}|}$$

- Fromm 
$$S_j = \min \text{mod} \left[ \frac{1}{2} (\Delta_{j-1/2} \mathbf{U} + \Delta_{j+1/2} \mathbf{U}), 2 \Delta_{j-1/2} \mathbf{U}, 2 \Delta_{j+1/2} \mathbf{U} \right]$$

- Van Albada 
$$S_j = \frac{(\Delta_{j+1/2} \mathbf{U})^2 \Delta_{j-1/2} \mathbf{U} + (\Delta_{j-1/2} \mathbf{U})^2 \Delta_{j+1/2} \mathbf{U}}{(\Delta_{j-1/2} \mathbf{U})^2 + (\Delta_{j+1/2} \mathbf{U})^2}$$
- And so on,



**Linearity Breeds Contempt.**  
– Peter Lax

# Role of modified equation analysis

- HHL '76 established positivity of coefficients and prelude to TVD, and entropy conditions via vanishing viscosity
- The entropy condition was derived via the modified equation analysis, first order produces a viscous term as the leading truncation error (modified equation).
  - This mode of analysis largely disappeared with the focus moving to discrete conditions providing nonlinear stability
- **Can modified equation analysis be engaged provide more benefits to modern methods?**

# Vanishing viscosity and entropy satisfying schemes

- The concept of vanishing viscosity is essential

$$\partial_t u + \partial_x f(u) = \nu \partial_{xx} u$$

$\nu \rightarrow 0^+$

- Another key concept is the nature of true limiting solution – for the linear waves – entropy generation converges to a limit of zero

$$\partial_t S + \partial_x (uS) = \frac{\nu}{T} \left( \partial_x u \right)^2 \geq 0$$

$\nu \rightarrow 0^+, h \rightarrow 0$

- For nonlinear waves the solutions **do not converge to a limit of zero** entropy production. The limit is finite entropy production.
- $$\partial_t S + \partial_x (uS) = \frac{\nu}{T} \left( \partial_x u \right)^2 - C f''(\Delta u)^3$$
- $\nu \rightarrow 0^+, h \rightarrow 0$

A fundamental limit for Euler, MHD, Burgers (and turbulence! Kolmogorov's third law) – dissipation in the absence of viscosity!

# A Framework for Analysis and Understanding

- Analyze energy, a quadratic function

$$U \cdot (U_t + \nabla \cdot [F(U) - \tau(U)]) = 0$$

$$E_t + \nabla \cdot U[F(U) - \tau(U)] = [F(U) - \tau(U)] \nabla U$$

- Total variation- 1D

$$\left| V \right|_t + F' \frac{\partial}{\partial x} \left[ \left| V \right| - \tau(V) \right] + HOT = 0 \quad V = \frac{\partial U}{\partial x}$$

**We will stick to linear equations for TV analysis**

# High Resolution Methods and their Modified Equation

- Nonlinear terms - associated with the limiters

$$\tau(U) = ch^2 |F'(U)| \frac{|U_x U_{xx}|}{U_x} \leftarrow \begin{array}{l} \text{minmod, or} \\ \text{mineno} \end{array}$$

$$\tau(U) = ch^3 |F'(U)| \frac{|U_x U_{xxx}|}{U_x} \leftarrow \text{UNO}$$

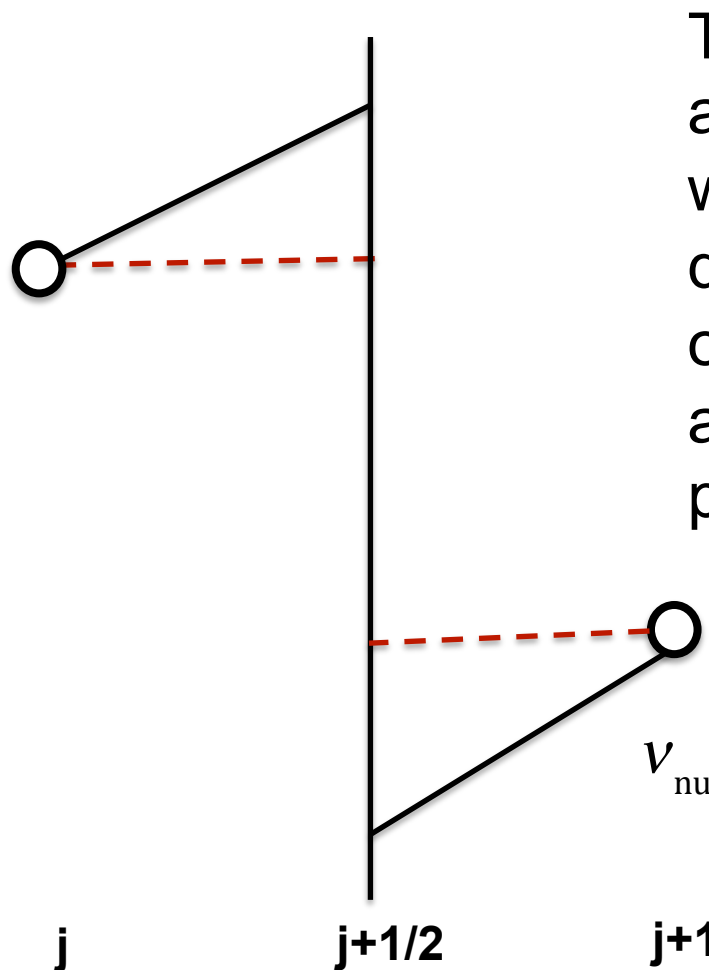
$$\tau(U) = ch^3 |F'(U)| \frac{(U_{xx})^2}{U_x} \leftarrow \text{WENO-3rd}$$

$$\tau(U) = ch^5 |F'(U)| \frac{(U_{xxx})^2}{U_x} \leftarrow \text{WENO-5th}$$

# Form for the effective artificial viscosities

- 1<sup>st</sup> order  $\nu_{\text{numerical}} = ch \left| F'(U) \right|$
- 2<sup>nd</sup> order  $\nu_{\text{numerical}} = ch^2 \left| F'(U) \right| \left| \frac{U_{xx}}{U_x} \right|$  **A limiter will control the magnitude**
- minmod  $\nu_{\text{numerical}} = ch^3 \left| F'(U) \right| \left| \frac{U_{xxx}}{U_x} \right|$   $\nu_{\text{numerical}} = ch^3 \left| F'(U) \right| \left( \frac{U_{xx}}{U_x} \right)^2$
- 3<sup>rd</sup> order
- TVD or ENO
- 5<sup>th</sup> order  $\nu_{\text{numerical}} = ch^5 \left| F'(U) \right| \frac{(U_{xxx})^2}{(U_x)^2}$
- WENO
- Implications – Limiters are needed to control the size of the viscosity. Schemes without limiters (ENO-WENO) may have too large a viscosity when the solution highly under-resolved.
- As I will discuss this may produce robustness issues for these schemes and can be “easily” seen by examining edge values.

# A reason why entropy-stable ENO schemes might actually have fragile non-robust side



This circumstance is “entropy stable” and a recipe for disaster especially with a Lax-Friedrichs flux. Too much dissipation can yield instability and oscillations. ENO schemes can do this and there is no extra nonlinear stability principle being applied to rescue it.

$$v_{\text{numerical}} = c_1 h^3 \left| F'(U) \right| \left| \frac{U_{xxx}}{U_x} \right| + c_2 h^3 \left| F'(U) \right| \left| \frac{U_{xxx}}{U_{xx}} \right| \frac{U_{xx}}{U_x}$$

$c_1 = \frac{1}{6} > c_2 = \frac{1}{12} \text{ or } \frac{1}{24}$

**A consequence of no bounds on the “viscosity” coefficient!**


# Energy Analysis

$$O(\Delta x)^2$$

- Stick with 1-D for simplicity' s sake

$$(\tau(U))_x = \left( c(U_x)^2 \right)_x$$

This is the “control volume” term

$$\rightarrow U(\tau(U))_x = \left( cU(U_x)^2 \right)_x - c(U_x)^3$$


For convex fluxes this term produces appropriate entropy production congruent with important physical laws. (SS-LES)

Margolin, Len G., and William J. Rider. "A rationale for implicit turbulence modelling." *International Journal for Numerical Methods in Fluids* 39, no. 9 (2002): 821-841.

$$(\tau(U))_x = (U_{xx})_x \quad \text{The dispersion term conserves energy}$$

$$\rightarrow U(\tau(U))_x = (cUU_{xx})_x - \frac{1}{2} \left( c(U_x)^2 \right)_x$$



# Analysis results - Variation

- Variation results all share a common theme. Variation is conserved except at sign changes in the derivatives.
- Easily shown for first order upwind.

$$|V|_t + |V|_x = \left( \lambda |V|_x \right)_x ; \lambda = |F'| \frac{\Delta x}{2} \left( \lambda |V|_x \right)_x = \lambda |V|_{xx} + \lambda \text{sign}'(V) (V_x)^2$$

- The variation is conserved except at sign changes then dissipated proportional to the first derivative

# What about TV results for high resolution schemes?

- Upwind – variation diminishing term

$$-\lambda(\Delta x) \text{sign}'(V) (V_x)^2$$

- Minmod

$$\lambda(\Delta x)^2 \left( \text{sign}'(V) \frac{1}{12} V_x V_{xx} - \frac{1}{4} \text{sign}'(V_x) (V_{xx})^2 \right)$$

- Third-order ENO

$$-\lambda(\Delta x)^3 \text{sign}'(V_{xx}) (V_{xxx})^2 \left[ \frac{1}{12} (1 + \text{sign}(V) \text{sign}(V_x)) + \frac{1}{24} (1 + \text{sign}(V_x) \text{sign}(V_{xx})) \right]$$

- Third-order ENO-like scheme (uses the “comparison” principle described later)

$$-\lambda \frac{1}{12} (\Delta x)^3 \text{sign}'(V_{xx}) (V_{xxx})^2$$

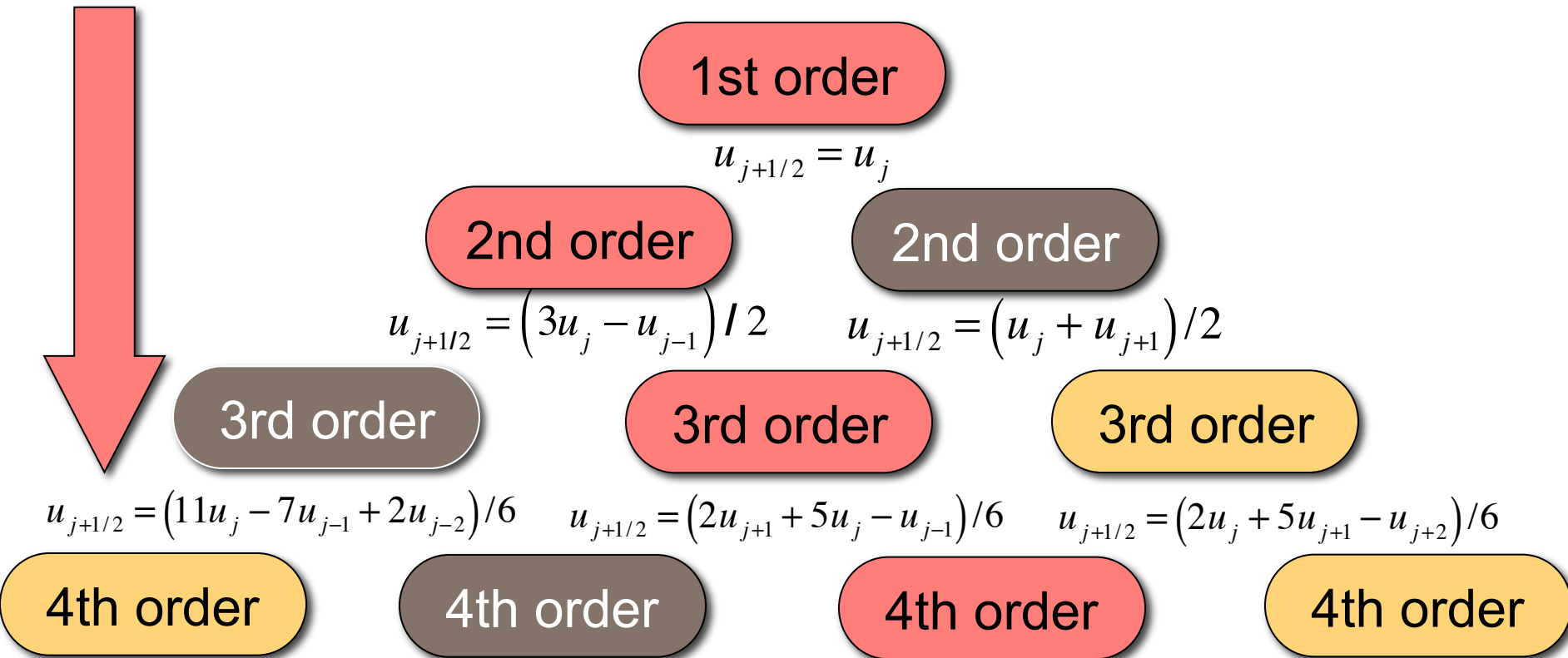
- Fifth-order WENO

$$-\lambda(\Delta x)^5 \text{sign}'(V) \left( \frac{1}{60} V_{xxxxx} - \frac{1}{20} \frac{(V_x)^2 (V_{xx})^2}{V^2} + \frac{1}{10} \frac{V_x V_{xx} V_{xxx}}{|V|} \right)$$

“The trick to forgetting the big picture  
is to look at everything close up.”

— Chuck Palahniuk

# ENO Methods use smoothness to adaptively choose a stencil.



- ENO selects stencils **adaptively** by choosing the one that is closest to the next lower order. It is hierarchical.

# The same differencing may be arrived at through a different path.

1st order

$$u_{j+1/2} = u_j$$

2nd order

$$u_{j+1/2} = (3u_j - u_{j-1})/2$$

2nd order

$$u_{j+1/2} = (u_j + u_{j+1})/2$$

3rd order

$$u_{j+1/2} = (11u_j - 7u_{j-1} + 2u_{j-2})/6$$

3rd order

$$u_{j+1/2} = (2u_{j+1} + 5u_j - u_{j-1})/6$$

3rd order

$$u_{j+1/2} = (2u_j + 5u_{j+1} - u_{j+2})/6$$

4th order

4th order

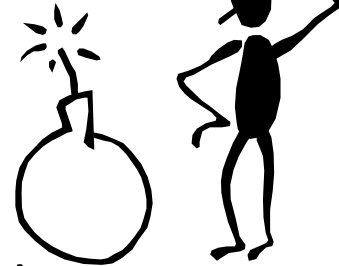
4th order

4th order

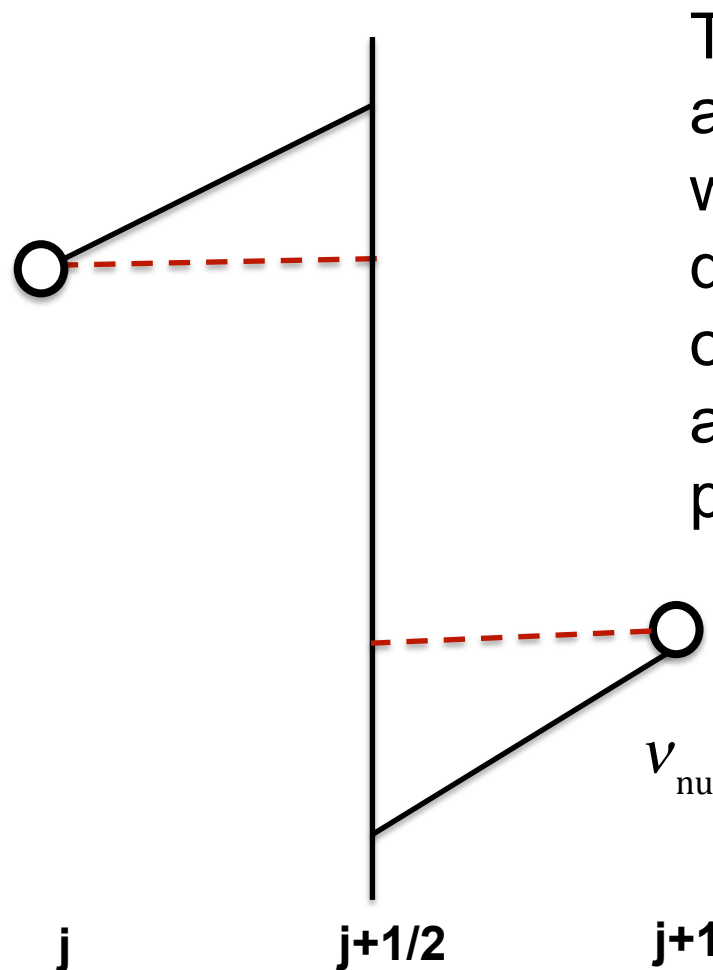
- The high-order stencils are evaluated pair-wise. This characteristic also hints at one of ENO's pathologies.

# Issues with ENO and WENO

- ENO can produce biased stencils that are linearly unstable (one reason for WENO).
  - Unstable dissipation due to poor edge value selection
- WENO methods are still somewhat oscillatory for very high-order (7th order and higher using a monotone limiter to control these oscillations, *inelegant*).
- The methods are still excessively dissipative (not always!) compared with other high-resolution methods.
- These methods are somewhat difficult to code (especially the smoothness detectors for >7th order), and analysis is even worse.



# A reason why entropy-stable ENO schemes might actually have fragile non-robust side



This circumstance is “entropy stable” and a recipe for disaster especially with a Lax-Friedrichs flux. Too much dissipation can yield instability and oscillations. ENO schemes can do this and there is no extra nonlinear stability principle being applied to rescue it.

$$v_{\text{numerical}} = c_1 h^3 \left| F'(U) \right| \left| \frac{U_{xxx}}{U_x} \right| + c_2 h^3 \left| F'(U) \right| \left| \frac{U_{xxx}}{U_{xx}} \right| \frac{U_{xx}}{U_x}$$

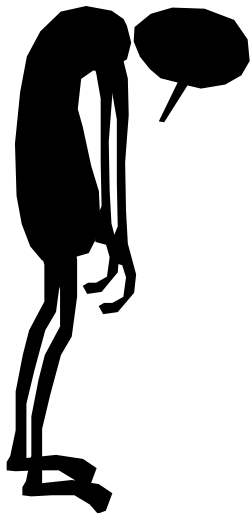
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**A consequence of no bounds on the “viscosity” coefficient!**

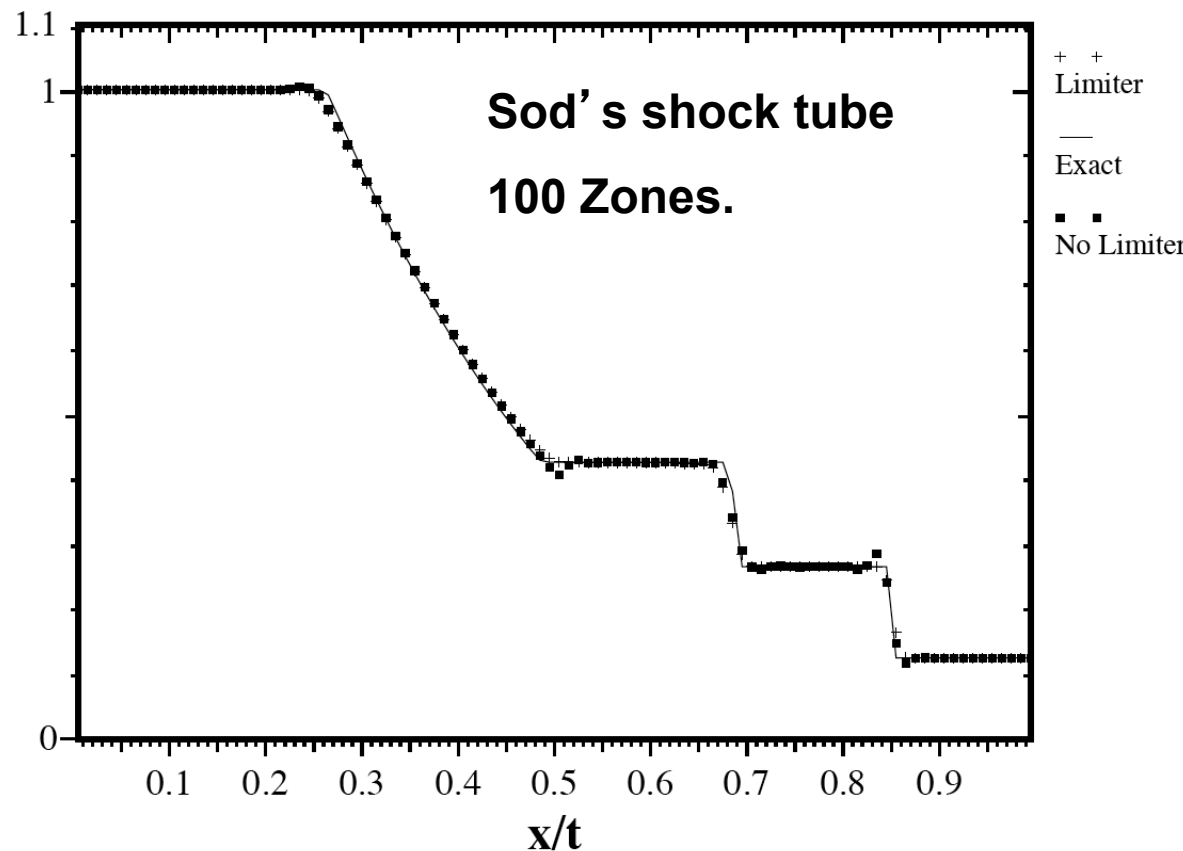
# Issues with Results - oscillations or limiters?

- Sod's shock tube and 11th order WENO

- Oscillations w/o limiter!
- The limiter destroys the “elegance” of the method!



Density!





# Three reasons why methods have stalled

- **Reason 1:** lack of smoothness in real problems and failed utility for formally high-order accurate methods
- **Reason 2:** Removal of the first-order method as a path for achieving robustness
  - Loss of second-order might be as detrimental too because of the value of the control volume term
- **Reason 3:** Use of much weaker nonlinear stability mechanisms and new potential instability mechanisms

“Change almost never fails because  
it's too early. It almost always fails  
because it's too late.”

— Seth Godin

# Three proposed principles for moving beyond monotonicity preservation in production codes.

- **Principle 1:** Use a nonlinear stability mechanism that detects extrema and carefully relaxes from monotonicity preservation
- **Principle 2:** Continue to use the high-order base scheme unless it violates monotonicity
- **Principle 3:** Apply additional dissipation at strongly nonlinear discontinuities. If the solution is under-resolved give up high-order accuracy and degenerate to first-order.

# An “ENO” method based on a TVD

## Comparison Principle

- The current ENO (and WENO) algorithms are based on the adaptive stencil approach that *recursively* finds the “smoothest” stencil.
- Use a different principle than the smoothest stencil - **Using a comparison with a TVD scheme to choose the high-order stencil.**
- In other words, one would begin with a TVD stencil and choose the higher-order stencil that is closest to that TVD stencil in some well-defined sense.
- Similar idea in principle to work by Suresh & Huynh, Rider Greenough & Kamm, and Colella & Sekora – all extrema preserving methods



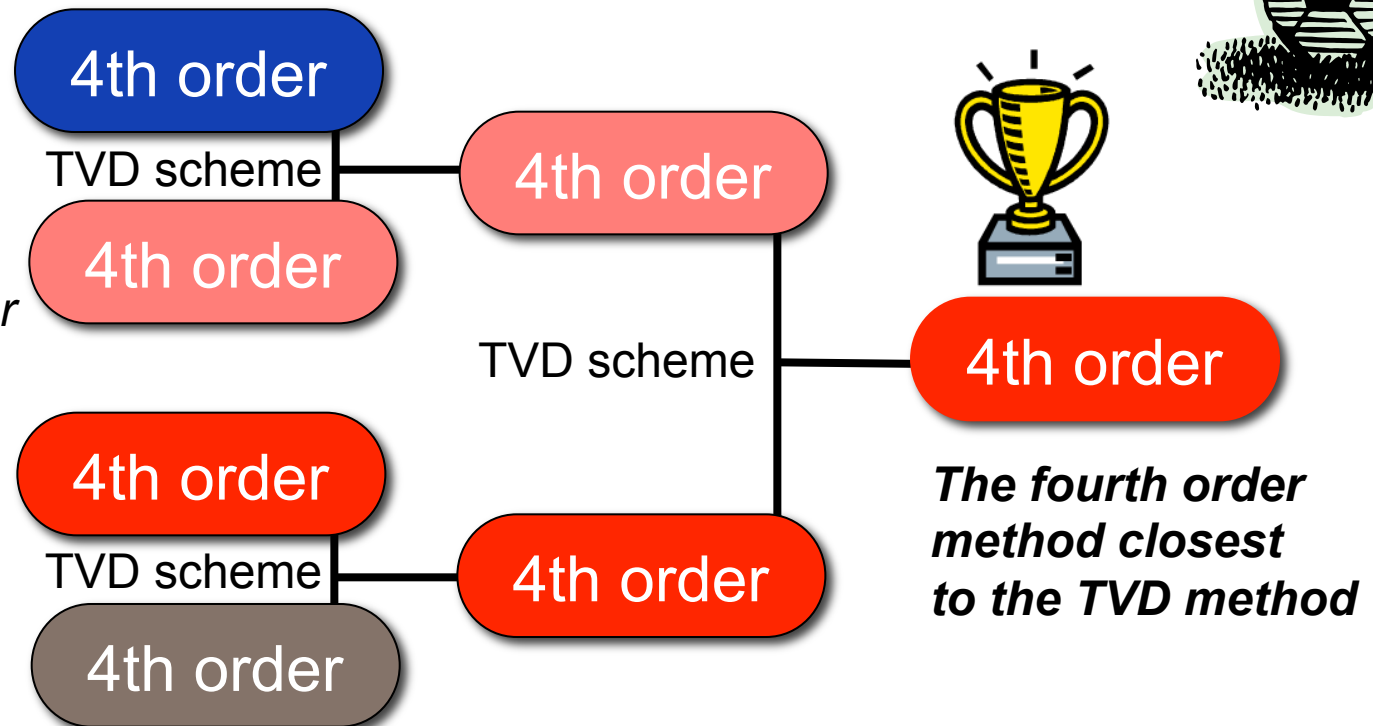
# The TVD comparison algorithm can be arranged like a tournament

The TVD scheme chosen for comparison is used to test the “fitness” of each high-order method. The method’s “fitness” is determined by its “closeness” to the TVD method.

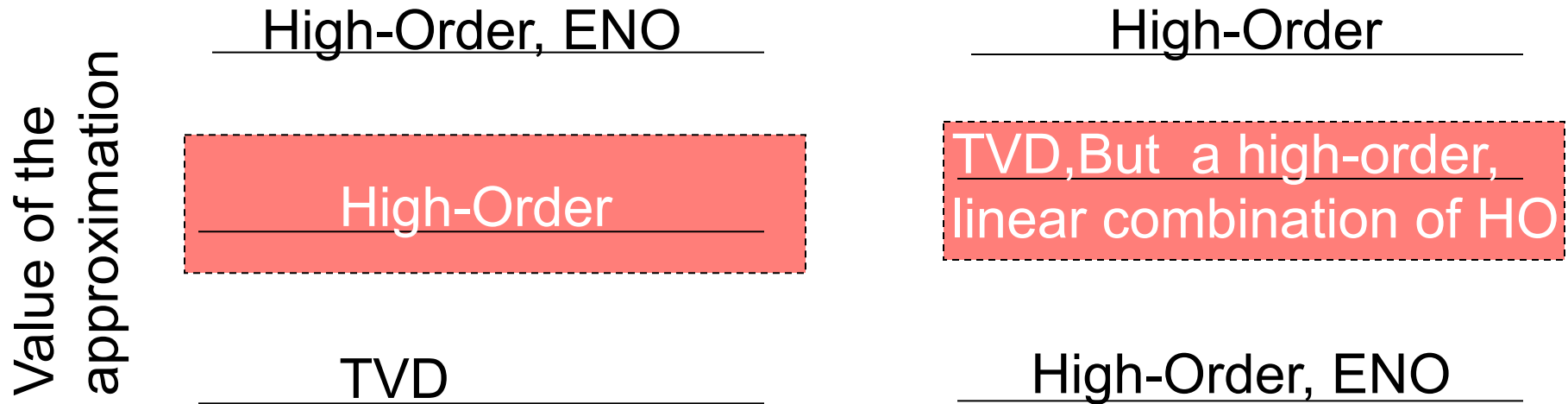
One of these  
4<sup>th</sup> order methods  
is upstream-  
centered

*The same or another  
4<sup>th</sup> order method  
would be the same  
as the ENO flux*

**We have accuracy,  
linear & nonlinear  
stability**



# The median function bounds the different approximations.



The  $\text{median}(a,b,c)$  returns the value bounded by the other two values. Preserves the accuracy given by at least two arguments.

*Conjecture:* If two arguments produce a linearly stable method, the **median** will as well.

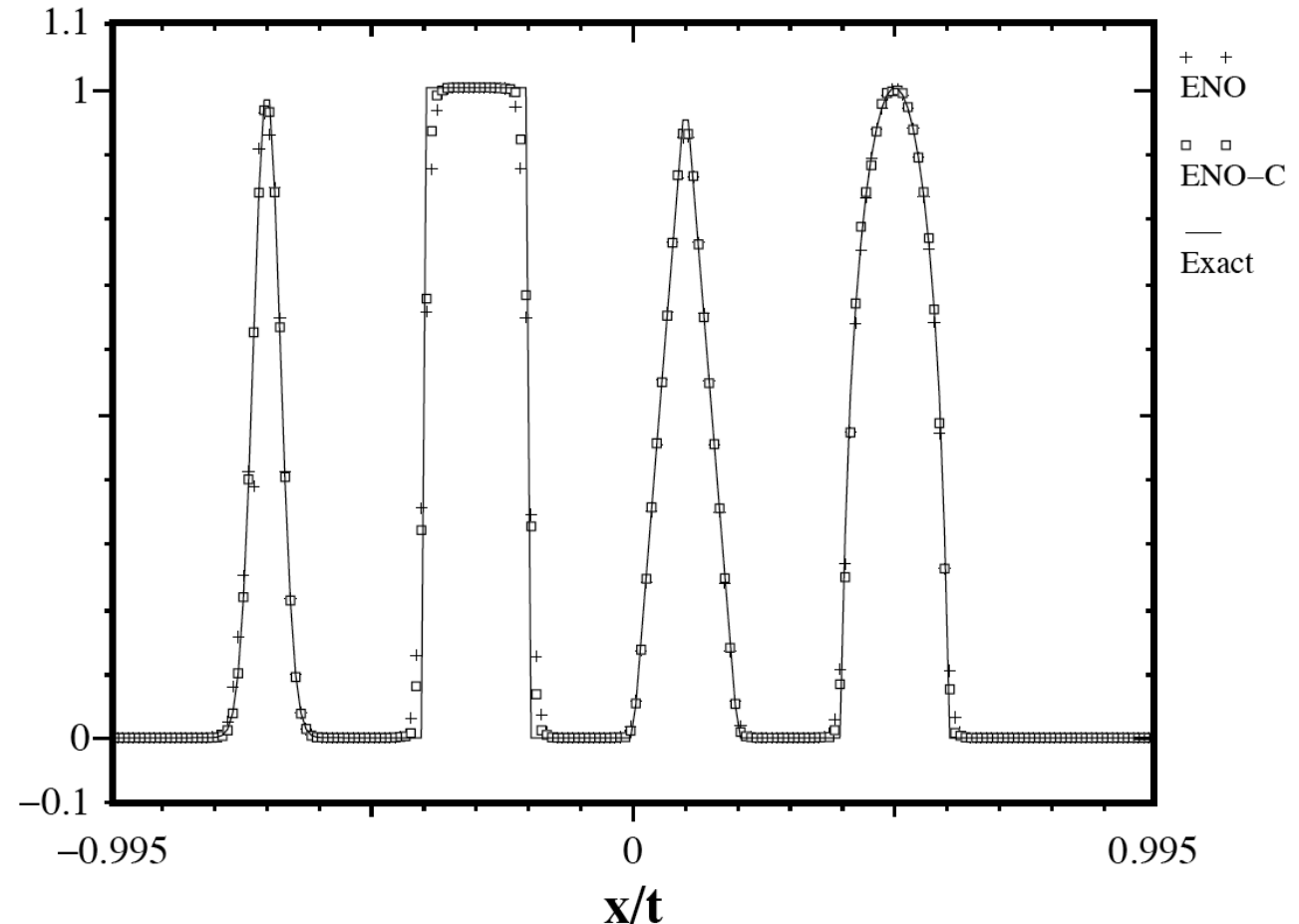
# Results: Accuracy on Scalar Waves

- Compare usual ENO with a comparison ENO

L1 Errors

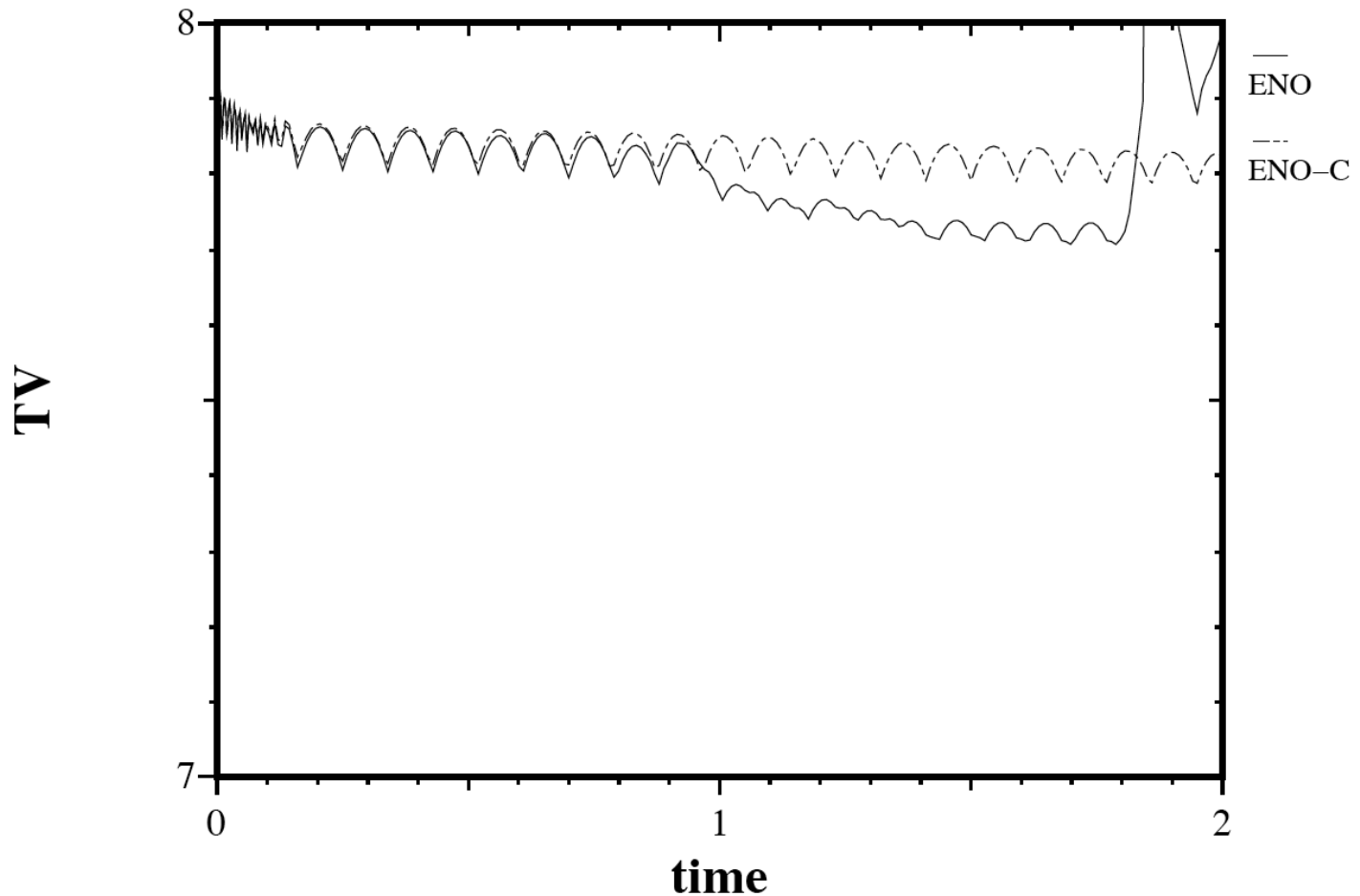
ENO =  $1.74\text{e-}02$

ENO-C =  $1.20\text{e-}02$



# Results: Total Variation Behavior

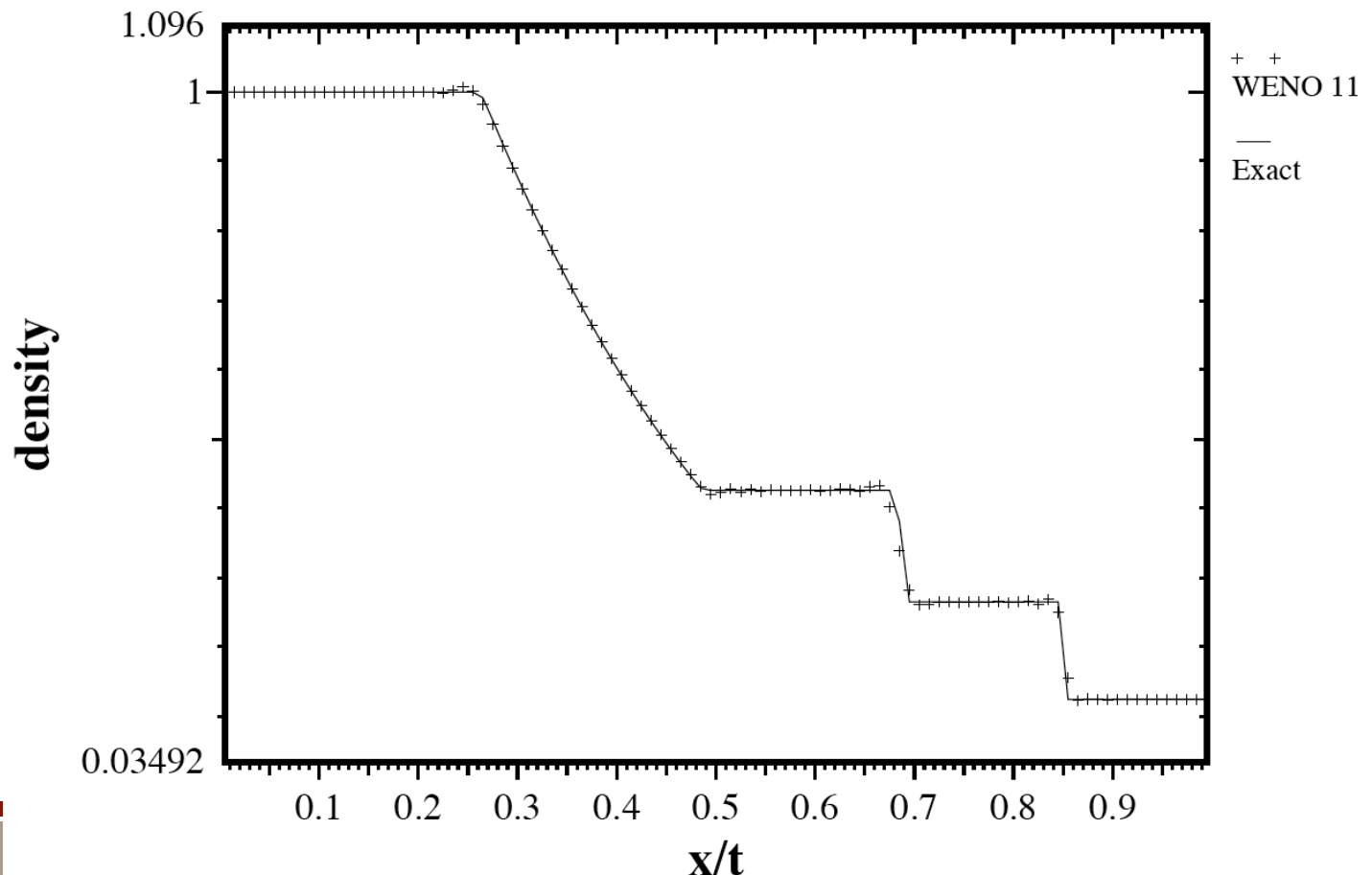
- Look experimentally at the Total variation as a function of time.





# Accuracy for Coupled Systems

- Look at Sod's Shock tube again w/11th order WENO-C (comparison scheme) - about the same as the regular WENO, and with about 25% lower CPU cost.



# Closing Thoughts

- Occam's Razor, "*It is vain to do with more what can be done with less,*" simplicity is a virtue
- **Simulations are ultimately discrete** - *discrete/nonlinear stability is an asset*
- **Modified equation analysis forms a systematic bridge between the discrete and continuous.**
  - **It has been underutilized!**
- Modeling and numerics is notoriously hard (if not impossible) to separate, but development of each is typically independent - this is a problem

“Some people see the glass half full.  
Others see it half empty. I see a  
glass that's twice as big as it needs  
to be.”

— George Carlin

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